Linear algebra: regression Statistical Natural Language Processing 1

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University of Tübingen Seminar für Sprachwissenschaft

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Quick recap

So far we reviewed:

- Vectors, matrices
- Operations on vectors and matrices: scalar multiplication, addition, dot product, matrix multiplication
- Matrices as operators (linear functions / transformations)
- Linearity and linear combinations
- Solving systems of linear equations, elimination
- Finding matrix inverse

Recap: solutions to systems of linear equations

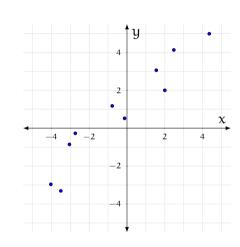
For a $n \times m$ matrix **A**

- Square, n = m
 - Unique solution if A is full rank n = r
 - Otherwise,
 - Infinite solutions if **b** is in the column space of **A**
 - No solutions otherwise
- Rectangular, n < m (wide matrix)
 - Infinite solutions if **b** is in the column space of **A**
 - No solutions otherwise
- Rectangular, n > m (tall/thin matrix)
 - Unique solution if **b** is in the column space of **A**
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Linear regression is about finding a linear *model* of the form,

$$y = w_1 x + w_0$$

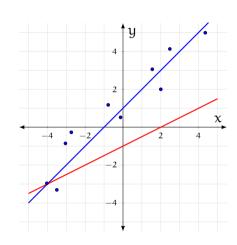
- y is a numeric quantity we want to predict
- x is a measurement/value helpful for predicting y
- w_0 and w_1 are the parameters that we want to learn from data
- both x and y can be vector valued



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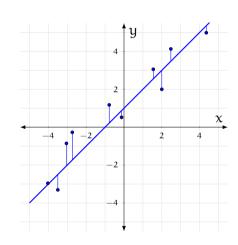
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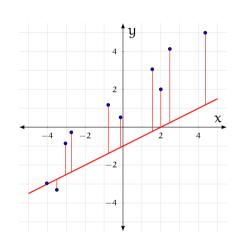
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Linear regression: and alternative view

this lecture

- Linear regression is also about finding the closest solution to a system of equations without a solution
- Given a dataset like

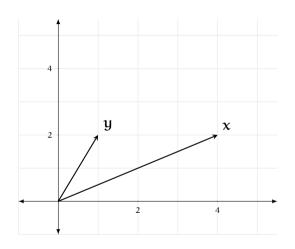
\mathbf{x}_1	\mathbf{x}_2	y
250.39	5.21	4913.19
332.18	3.77	59.67
312.47	1.26	154.42
272.01	7.01	166.27

- Find the closest solution to Xw = y
- In other words, we solve Xw = p, where p is a vector that allows the system to be solved, and it the closest such vector to y

A simple example

• Let's take

$$\mathbf{x} = \begin{bmatrix} 4 \\ 2 \end{bmatrix} \quad \mathbf{y} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$



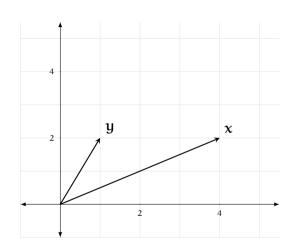
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$$xw = y$$



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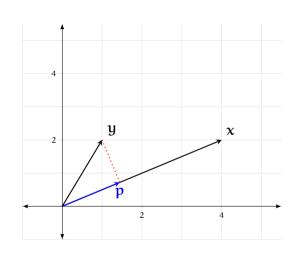
• We want to solve,

$$xw = y$$

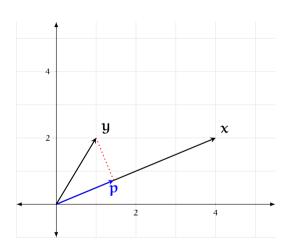
• Instead we solve,

$$xw = p$$

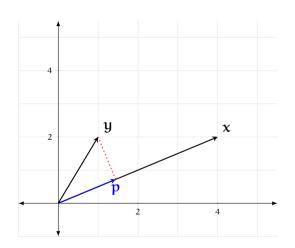
where p is the orthogonal projection of y onto the line defined by x



• \mathbf{p} is a scalar multiple (linear combination) of \mathbf{x} : $\mathbf{p} = \mathbf{x}\mathbf{w}$

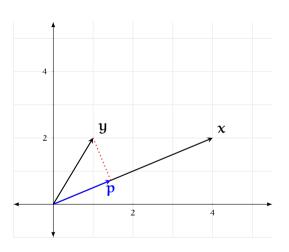


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- We get the projection, if we multiply this with the unit vector in x direction

$$p = \frac{x}{\|x\|} \frac{x^T y}{\|x\|} = \frac{x x^T}{\|x\|^2} y = \frac{x x^T}{x^T x} y$$

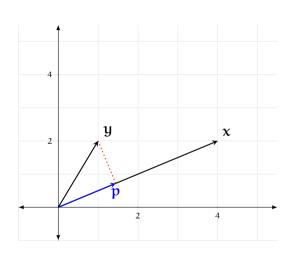


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$$p = \frac{\mathbf{x}}{\|\mathbf{x}\|} \frac{\mathbf{x}^\mathsf{T} \mathbf{y}}{\|\mathbf{x}\|} = \frac{\mathbf{x} \mathbf{x}^\mathsf{T}}{\|\mathbf{x}\|^2} \mathbf{y} = \frac{\mathbf{x} \mathbf{x}^\mathsf{T}}{\mathbf{x}^\mathsf{T} \mathbf{x}} \mathbf{y}$$

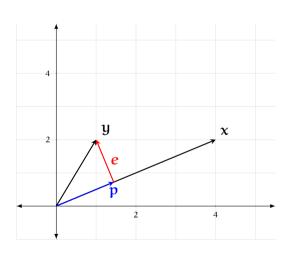
• w, in this case is also easy:

$$w = \frac{\mathbf{x}^\mathsf{T} \mathbf{y}}{\mathbf{x}^\mathsf{T} \mathbf{x}}$$



a slightly different explanation

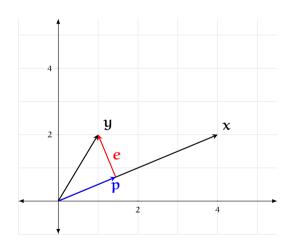
• Note that e = y - p



a slightly different explanation

- Note that e = y p
- Since *x* and *e* are orthogonal

$$\mathbf{x}^{\mathsf{T}}(\mathbf{y} - \mathbf{x}w) = 0$$
$$\mathbf{x}^{\mathsf{T}}\mathbf{y} = \mathbf{x}^{\mathsf{T}}\mathbf{x}w$$
$$w = \frac{\mathbf{x}^{\mathsf{T}}\mathbf{y}}{\mathbf{x}^{\mathsf{T}}\mathbf{x}}$$



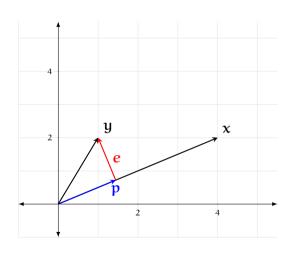
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$$\mathbf{w} = \frac{\mathbf{x}^{\mathsf{T}}\mathbf{y}}{\mathbf{x}^{\mathsf{T}}\mathbf{x}}$$

• Since we defined p = xw,

$$p = x \frac{x^T y}{x^T x} = \frac{x x^T}{x^T x} y$$



Solution to the simple regression example

For our example,

• Our 'training' gives us

$$w = \frac{\mathbf{x}^\mathsf{T} \mathbf{y}}{\mathbf{x}^\mathsf{T} \mathbf{x}}$$

 For future x values, the prediction of y is

$$y = wx$$

$$\mathbf{x} = \begin{bmatrix} 4 \\ 2 \end{bmatrix} \quad \mathbf{y} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

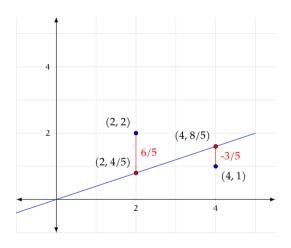
- $w = \frac{2}{5}$
- The model:

$$y = \frac{2}{5}x$$

Questions:

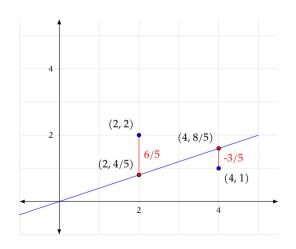
- what is the error e on the training instances?
- what is $e^{T}x$?

• The model: $y = \frac{2}{5}x$



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- Predictions:

$$p = \begin{bmatrix} 4 \times 2/5 \\ 2 \times 2/5 \end{bmatrix} = \begin{bmatrix} 8/5 \\ 4/5 \end{bmatrix}$$

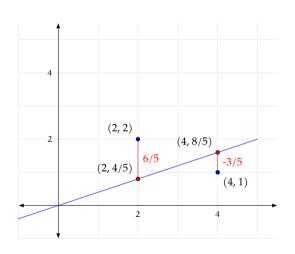


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• Error:

$$e = \begin{bmatrix} 1 \\ 2 \end{bmatrix} - \begin{bmatrix} 8/5 \\ 4/5 \end{bmatrix} = \begin{bmatrix} -3/5 \\ 6/5 \end{bmatrix}$$



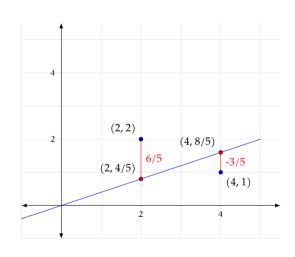
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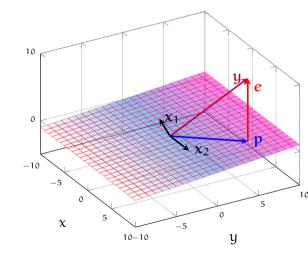
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• Is this a good model?



Linear regression in higher dimensions

- In higher dimensional spaces we want the projection onto the column space of X
- The error vector e is perpendicular to all column vectors of X, x_i
- Again, note that e = y p



Deriving linear regression on higher dimensions

$$X^{T}(y-p) = 0$$
 Error vector is orthogonal to columns $X^{T}(y-Xw) = 0$ p is the weighted combination of columns $X^{T}Xw = X^{T}y$ Note: $X^{T}X$ is square $w = (X^{T}X)^{-1}X^{T}y$ The final solution

The projection of y onto columns space of X is

$$\mathbf{p} = \mathbf{X}(\mathbf{X}^{\mathsf{T}}\mathbf{X})^{-1}\mathbf{X}^{\mathsf{T}}\mathbf{y}$$

The intercept (bias) term

• The models we fit so far are 'linear',

$$y = w_1 x_1 + w_2 x_2 + \ldots + w_m x_m$$

they are forced to include y = 0 for x = 0

• In most (almost all) cases, this is too restrictive, we also want to learn an intercept term

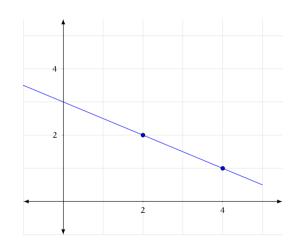
$$y = w_0 + w_1 x_1 + w_2 x_2 + ... + w_m x_m$$

ullet A straightforward solution is to include an artificial column of 1s in the input matrix old X

$$X = \begin{bmatrix} 1 & 4 \\ 1 & 2 \end{bmatrix} \quad y = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

Solution with the intercept term

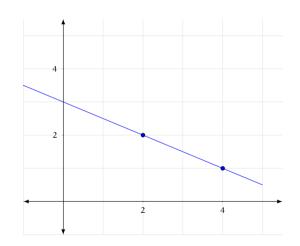
• Solution: $w_0 = 3$, $w_1 = -1/2$



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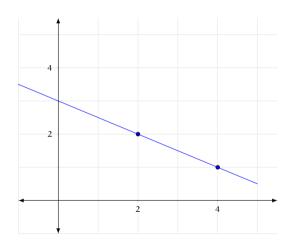
• Solution: $w_0 = 3$, $w_1 = -1/2$

• The model: y = 3 - 1/2x



Solution with the intercept term

- Solution: $w_0 = 3$, $w_1 = -1/2$
- The model: y = 3 1/2x
- Is this a better model?



Regression in the real world

- In this lecture, we focused on finding the best fit to the data
- This may (very likely) result in *overfitting*
- To prevent overfitting, we
 - use regularization
 - never rely on performance on the training set, success should only be measured on a *held-out* data set
- We will return to these concepts later

Summary / next

- We reviewed regression as a way to find an approximate solution to a system of linear equations
- We will come back to regression multiple times

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Next:

• Determinant, eigenvalues/eigenvectors, SVD

Further reading

Any of the linear algebra references provided earlier.