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Left and right inverses	Computing pseudo inverse
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	+ We want matrix multiplication to get as close to I as possible. Consider the 3×4 diagonal matrix:
 For a non-square matrix, or a square matrix with rank lower than n, the inverse is not defined 	[1/0 0 0] [1 0 0 0]
 From linear regression, we know that (X^TX)⁻¹X^T acts as a left inverse Similarly we can define right inverse as X^T(XX^T)⁻¹ 	
 Remember, however, the existence of (X^TX)⁻¹ requires columns of X to be 	$ \begin{bmatrix} 1/\alpha & 0 & 0 \\ 0 & 1/b & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \times \begin{bmatrix} \alpha & 0 & 0 & 0 \\ 0 & b & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0$
independent	* For an $n\times n$ diagonal matrix $\Sigma,\Sigma^+-\Sigma^{-1}$
A more general solution falls out of SVD	 For any invertible n × n matrix X, X⁺ = X^{−1}
	* In general, if we use singular value decomposition $X^+ = V \Sigma^+ U^T$
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Summary / next	Further reading
 We reviewed SVD and pseudo inverse SVD is a very important method. We will return to it multiple times during 	
the course	Any of the linear algebra references provided earlier.
Next: • A very short introduction to calculus	
the SVD song	
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